Robust sampling design for spatially explicit capture–recapture Murray Efford

EURING, Montpellier, April 2023

SECR models

State model





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Previously...

Efford et al. (2005) Brushtail possums in New Zealand



1 km

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Algorithmic solution (Dupont et al. 2021, Durbach et al. 2021):

- Seek optimal subset X of potential locations
- Genetic algorithm in R package kofnGA (Wolters 2015)
- Maximise an objective function e.g., f(X) = min(E(n), E(r)) using pilot values of λ₀, σ etc.

n = number of individuals detected

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Algorithmic optimisation - three examples



varying random seed, similar objective value

Evaluate algorithmic optimisation by simulation

Methods -

- parameter values based loosely on possum study
- uniform random (Poisson) activity centres
- report
 - accuracy: relative $\text{RMSE}(\hat{D})$
 - coverage of 95% confidence intervals for \hat{D}



RMSE 10.8% COV 93.2% RMSE 7.7% COV 94.4%

2-D Poisson activity centres. 500 replicates

Algorithmic optimisation, in summary

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Sampling is representative by accident, if at all

What if distribution unknown, and not uniform?

e.g., 50% random habitat



Unmodelled heterogeneity x unrepresentative sampling



2-D Poisson, 50% habitat



Representative sampling by design

Many options. I compare -

1 Simple random sample of detector locations

2 Clusters at centroids of compact spatial strata

- 'spatial coverage sample' Walvoort et al. (2010)
- 3 Lacework
 - R package 'secr'

Comparing representative designs



CI coverage adjusted for overdispersion, Fletcher's \hat{c}





- Current 'optimisation' algorithms fail to deliver for large and potentially heterogeneous areas
- Spatially representative designs are robust to non-uniform distribution
- Spatial overdispersion should be taken seriously

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